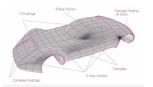
Dimension formula of generalized splines of degree 2

Anne Schilling

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based on joint work with Shaheen Nazir (Lahore University) and Julianna Tymoczko (Smith College)



Women in Algebra and Combinatorics SUNY Albany April 30, 2023

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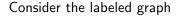
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The collection of all splines on (G, α) forms a ring and an R-module with vertex-wise addition, multiplication, and scaling.

Consider the labeled graph



Label vertices so that p(u) - p(v) is a multiple of $\alpha(uv)$





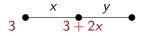
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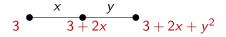
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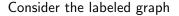


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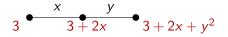
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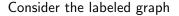




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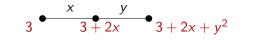


Basis for splines:



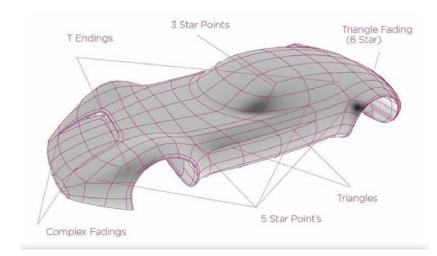


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Basis for splines:





Splines for Meshes with Irregularities, J. Peters, SMAI journal of computational mathematics, 2019.

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What are splines? (context)

 Our definition of splines is dual (in an algebraic sense) to the classical definition of splines.

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- Our definition coincides with a combinatorial construction of equivariant cohomology called GKM theory. GKM theory gives conditions on a variety X with the action of a torus T so that
 - the *T*-fixed points and one-dimensional *T*-orbits form a graph G_X
 - when the edges of G_X are labeled with the T-weights then

 $H^*_T(X) \cong$ splines on (G_X, α_X)

The upper-bound conjecture asks for a dimension formula for splines of degree at most d and smoothness r on triangulated regions in the plane.

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- and **completely unknown** when *d* = 2.

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 - By translating the original triangulation, we can assume this about any individual face without loss of generality.

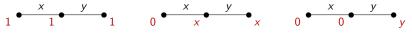
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We want a dimension formula for splines of degree 2

Splines on trees and cycles

Splines on trees have a straightforward basis:



(Generalized by Gilbert, Tymoczko, Viel)



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Splines on cycles are more complicated:

$$\begin{array}{c|c} p + c_1 \ell_1 & \ell_2 \\ \ell_1 & & \\ p & \ell_4 \end{array} \begin{array}{c} p + c_1 \ell_1 + c_2 \ell_2 \\ \ell_3 \\ p + c_1 \ell_1 + c_2 \ell_2 + c_3 \ell_3 \end{array}$$

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We get an equation $c_1\ell_1 + c_2\ell_2 + c_3\ell_3 + c_4\ell_4 = 0$ for each cycle

Let G = (V, E) be a finite, connected, planar graph.

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- A cycle in G is a sequence of vertices $v_1v_2 \dots v_k v_1$ such that $v_k v_1$ and each $v_i v_{i+1}$ are edges.
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An important question in topological graph theory is which cycles are independent in a reasonable sense, namely form a cycle basis.

Face cycle basis matrix

Order the edges $E = \{e_1, e_2, \ldots, e_{e_G}\}$ and the (bounded) faces $\mathcal{F} = \{F_1, F_2, \ldots, F_{f_G}\}$. The face cycle basis matrix M is the $f_G \times e_G$ matrix that is zero except 1 in row r and column c if edge e_c is an edge on face cycle of F_r .

$$e_1 \underbrace{ \begin{bmatrix} e_2 & e_5 & e_8 \\ & e_4 \end{bmatrix}}_{e_3 & e_6} e_7 \qquad M = \begin{pmatrix} 1 & 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 1 & 1 & 0 \end{pmatrix}$$

Extended face cycle basis matrix

In our case, edge-labels have the form $\ell_i = (a_i x + y)^2$. The equation

$$c_1\ell_1 + c_2\ell_2 + c_3\ell_3 + c_4\ell_4 = 0$$

becomes

$$c_1(a_1x + y)^2 + c_2(a_2x + y)^2 + c_3(a_3x + y)^2 + c_4(a_4x + y)^2 = 0$$

Rearranging gives

$$(c_1a_1^2 + c_2a_2^2 + c_3a_3^2 + c_4a_4^2)x^2 + (c_1a_1 + c_2a_2 + c_3a_3 + c_4a_4)2xy + (c_1 + c_2 + c_3 + c_4)y^2 = 0$$

This vanishes as a **polynomial** so each red coefficient is 0.

Extended face cycle basis matrix

The extended face cycle basis matrix M^{ext} replaces each row of the face cycle basis matrix with three rows, with column *i* zero if the original entry is zero, and $(1, a_i, a_i^2)^T$ if it's one.

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$$e_{1} \underbrace{\begin{array}{ccccc} e_{2} & e_{5} & e_{8} \\ e_{4} & e_{7} \\ e_{3} & e_{6} \end{array}}_{e_{3} & e_{6}} M^{\text{ext}} = \begin{pmatrix} 1 & 1 & 1 & 1 & 0 & 0 & 0 & 0 \\ a_{1} & a_{2} & a_{3} & a_{4} & 0 & 0 & 0 & 0 \\ a_{1}^{2} & a_{2}^{2} & a_{3}^{2} & a_{4}^{2} & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & a_{4} & a_{5} & a_{6} & a_{7} & 0 \\ 0 & 0 & 0 & a_{4}^{2} & a_{5}^{2} & a_{6}^{2} & a_{7}^{2} & 0 \end{pmatrix}$$

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The dimension of degree 2 splines

Theorem (Nazir, 5., Tymoczko 2023)

Let $\text{Spl}_2(G, \ell)$ be collection of degree two splines associated to the labelled, finite, planar graph (G, ℓ) . Then

 $\dim \operatorname{Spl}_2(G, \ell) = e_G - \operatorname{rank} M^{\operatorname{ext}}$

where e_G is the number of edges in G.

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When M^{ext} is full rank, the dimension of degree two splines is

 $e_G - 3f_G$.

When does this happen?

Note the 3×3 Vandermonde matrices with determinant

$$(a_i - a_j)(a_j - a_k)(a_i - a_k)$$

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- Square submatrices of M^{ext} have determinants related to these Vandermonde determinants.
- Generically when $a_i \neq a_j \neq a_k$ these determinants are nonzero.

Three is a special number for these splines.

An edge-injective function φ assigns to each face F in a planar graph G up to three (unordered) edges on the boundary of F so that no edge is assigned to more than one face. The **size** of an edge-injective function is the total number of edges in its image.

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Theorem (Nazir, S., Tymoczko 2023)

N is any square $3k \times 3k$ submatrix of M^{ext} . Then

$$\det N = \sum_{\substack{\varphi: \ \mathcal{F} \to \mathcal{E}_3 \\ edge-injective}} \prod_{F \in \mathcal{F}} \det N_{F,\varphi(F)},$$

 $N_{F,\varphi(F)}$ = submatrix of N with the 3 rows corresponding to F and columns indexed by $\varphi(F)$.

Algorithm: Dimension of degree 2 splines

The generic case is when det N is a nonzero polynomial in the labels a_i .

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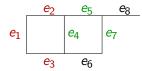
- Case $e_G \leq 3f_G$: dim Spl₂(G, ℓ) = 0.
- Case G no leaves and no subgraph G' with $e_{G'} \leq 3f_{G'}$: dim Spl₂(G, ℓ) = $e_G - 3f_G$.

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If G has contractible subgraph G' with $e_{G'} \leq 3f_{G'}$, contract G'.



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Dimension of degree 2 splines is 2 in general



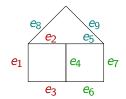
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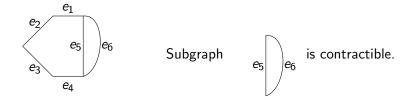
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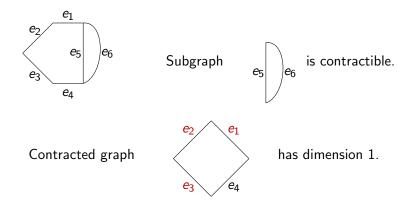
Dimension of degree 2 splines is 2 in general



Dimension of degree 2 splines is 0 in general a = b + a = b



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Existence of edge-injective functions

Theorem (Nazir, S., Tymoczko 2023)

If G is a finite, planar graph and contains no proper contractible subset of faces, there is an edge-injective function.

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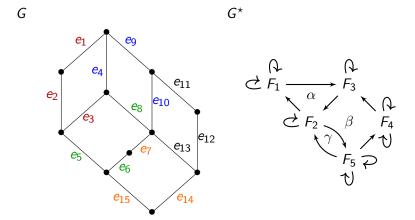
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Conjecture (Nazir, 5., Tymoczko 2023)

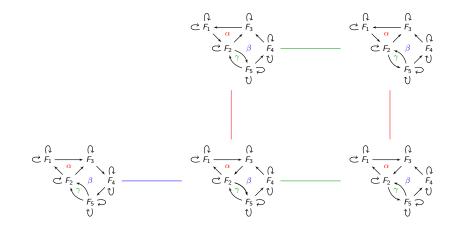
If G is a finite, planar graph, contains no proper contractible subset of faces, and no two faces share more than three edges, there exists a generic edge labeling.

Edge-injective function on dual graph



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Construction of all edge-injective functions



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- Computing the dimension of splines has a combinatorial aspect (existence of certain kinds of Euler paths/edge-injective functions/coloring of edges)
-and an algebraic aspect (whether certain determinants vanish or not).
- The combinatorial aspect governs the generic case, where we obtain a formula for degree 2 splines.

• The algebraic aspect determines the non-generic case.

Thank you!



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