Cyber-Physical Systems



Composite Models

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Side-by-Side Composition



Synchronous composition: the machines react simultaneously and instantaneously.



Cascade Composition



Synchronous composition: the machines react simultaneously and instantaneously, despite the apparent causal relationship!



Synchronous Composition

Consider a cascade composition as follows:



Reactions are Simultaneous and Instantaneous



Synchronous Dataflow (SDF)

- Specialized model for dataflow
- All actors consume input tokens, perform their computation and produce outputs in one atomic operation
- Flow of control is known (predictable at compile time)
- Statically scheduled domain
- Useful for synchronous signal processing systems
- Homogeneous SDF: one token is usually produced for every iteration





Multirate SDF Model

SDF Director

- The firing rates of the actors are not identical
- The Spectrum actor requires 256 tokens to fire, so one iteration of this model requires 256 firings of Sinewave, Channel, and SequencePlotter, and one firing of Spectrum.





Balance Equations



- > When A fires, it produces M tokens on its output port
- > When B fires, it consumes N tokens on its input port
- > M and N are non-negative integers
- > Suppose that A fires q_A times and B fires q_B times
- All tokens that A produces are consumed by B if and only if the following **balance equation** is satisfied

 $q_A M = q_B N$

The system remains in balance if and only if the balance equation is satisfied



Example



- ≻ Suppose M=2, N=3
- Possible Solution:
 - q_A=3, q_B=2
 - Example Schedule : {A, A, A, B, B} OR {A, B, A, A, B}
- > Another Possible Solution:
 - $q_A = 6, q_B = 4$
 - Example Schedule: {A,A,A,A,A,A,B,B,B,B}



Strategy for firing

- Streaming applications: arbitrarily large number of tokens
- Naive strategy: fire actor A an arbitrarily large number q_A times, and then fire actor B q_B times
 - Why naive?
- > Better strategy:
 - smallest positive q_A and q_B that satisfy the balance equation
- > Unbounded execution with bounded buffers



Solving the Balance Equation

- Every connection between actors results in a balance equation
- The model defines a system of equations, and the goal is to find the least positive integer solution



- > The least positive integer solution to these equations is
 - $q_A = q_B = 1$, and $q_C = 2$
- The schedule {A, B, C, C} can be repeated forever to get an unbounded execution with bounded buffers



Inconsistent SDF



- An SDF model that has a non-zero solution to the balance equations is said to be consistent.
- > If the only solution is zero, then it is inconsistent.
- An inconsistent model has no unbounded execution with bounded buffers.
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Feedback Loop

- A feedback loop in SDF must include at least one instance of the SampleDelay actor
- Without this actor, the loop would deadlock
 - actors in the feedback loop would be unable to fire because they depend on each other for tokens.
- The initial tokens enable downstream actors to fire and break the circular dependencies that would otherwise result from a feedback loop





Example Feedback Loop



- > The least positive integer solution is
- qA = 2, qB = 3, so the model is consistent.
- With 4 initial tokens: consistent
- > With 3 initial tokens: deadlock



Multirate Dataflow Actors

> actors that produce and/or consume multiple tokens per firing on a port





Dynamic Dataflow (DDF)

- SDF cannot express conditional firing: an actor fires only if a token has a particular value
- DDF: Firing Rule is required to be satisfied for firing
- Number of tokens produced can vary
- Example DDF Actor: Select
- Similar to Go To in Imperative Programming



Example DDF (Conditional Firing)



When Bernoulli produces true, the output of the Ramp actor is multiplied by -1



Data Dependent Iteration





Conditional Firing Output





Unbounded Buffer Schedule

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The Bernoulli actor is capable of producing an arbitrarily long sequence of true-valued tokens, during which an arbitrarily long sequence of tokens may build up on input buffer for the *false* port of the BooleanSelect, thus potentially overflowing the buffer.





- It may not be possible to determine a schedule with bounded buffers
- Not always possible to ensure that the model will not deadlock
- Buck (1993) showed that bounded buffers and deadlock are undecidable for DDF models.
- > DDF models are not as readily analyzed.
- Structured dataflow & higher order actors are used



Structured Dataflow

- Higher order actor: combine multiple actors as components
- Example Case: 2 sub-models
 - true that contains a Scale actor with a parameter of -1, and
 - default that contains a Scale actor with a parameter of 1.
 - When the control input to the Case actor is true, the true refinement executes one iteration. For any other control input, the default refinement executes.

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Actor Model Implementation

- > Multiple clocks
- > Multiple domains
- > Buffer: Queue
- > Message: Interprocess communication

